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# Numerical Preliminary Study on Designing Navigation and Stability Control Systems for ITS AUV

ORIGINALITY REPORT



PRIMARY SOURCES

- |   |  |    |
|---|--|----|
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| 4 | Oktafianto, Kresna, Teguh Herlambang, Mardlijah, and Hendro Nurhadi. "Design of Autonomous Underwater Vehicle motion control using Sliding Mode Control method", 2015 International Conference on Advanced Mechatronics Intelligent Manufacture and  | 2% |

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